

Chern-Simons Modified Gravity

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- We will present the Mathematical Formalism of the new theory and its implications

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- We will present the Mathematical Formalism of the new theory and its implications
- Then talk about vacuum solutions of the Chern-Simons theory in both the non-dynamical and the dynamical formalism

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- We will present the Mathematical Formalism of the new theory and its implications
- Then talk about vacuum solutions of the Chern-Simons theory in both the non-dynamical and the dynamical formalism
- We will focus **only** on axisymmetric (static and stationary) solutions that are also solutions of General Relativity

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$$S \equiv S_{EH} + S_{CS} + S_{\theta} + S_{\text{mat}} \quad (1)$$

With :

$$S_{EH} = \kappa \int_{\mathcal{V}} \sqrt{-g} R d^4x \quad (2a)$$

$$S_{CS} = \alpha \frac{1}{4} \int_{\mathcal{V}} \sqrt{-g} \theta {}^*R R d^4x \quad (2b)$$

$$S_{\theta} = -\beta \frac{1}{2} \int_{\mathcal{V}} \sqrt{-g} \left[g^{ab} (\nabla_a \theta) (\nabla_b \theta) + 2V(\theta) \right] d^4x \quad (2c)$$

$$S_{\text{mat}} = \int_{\mathcal{V}} \sqrt{-g} \mathcal{L}_{\text{mat}} d^4x \quad (2d)$$

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Where :

$$*R R \equiv *R_b^{acd} R_{acd}^b$$

is a quantity called *Pontryagin Density*.

It is of topological nature and connected to the following quantity, which is called the *Topological Current*, :

$$K^a \equiv \epsilon^{abcd} \Gamma_{bm}^n \left(\partial_c \Gamma_{dn}^m + \frac{2}{3} \Gamma_{cl}^m \Gamma_{dn}^l \right)$$

by :

$$*R R = 2 \nabla_a K^a$$

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We ask for :

$$\delta S = 0 \quad (1)$$

which yields :

$$\begin{aligned} \delta S &= \kappa \int_{\mathcal{V}} \sqrt{-g} \left(R_{ab} - \frac{1}{2} g_{ab} R + \frac{\alpha}{\kappa} C_{ab} - \frac{1}{2\kappa} T_{ab} \right) \delta g^{ab} d^4x \\ &+ \int_{\mathcal{V}} \sqrt{-g} \left[\frac{\alpha}{4} {}^*R R + \beta \square \theta - \beta \frac{dV}{d\theta} \right] \delta \theta d^4x \\ &+ \Sigma_{EH} + \Sigma_{CS} + \Sigma_{\theta} = 0 \end{aligned} \quad (2)$$

Σ_{EH} , Σ_{CS} and Σ_{θ} are surface terms which arise from integration by parts. They are generally vanishing.

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So the field equations are :

$$G_{ab} + \frac{\alpha}{\kappa} C_{ab} = \frac{1}{2\kappa} T_{ab} \quad (1)$$

and

$$\beta \square \theta = \beta \frac{dV}{d\theta} - \frac{\alpha}{4} {}^*R R \quad (2)$$

G_{ab} is just the Einstein tensor without a cosmological constant and C_{ab} is defined as follows :

$$C^{ab} \equiv u_{cd} {}^*R^{d(ab)c} + u_d \epsilon^{dce(a} \nabla_e R^b)_c \quad (3)$$

where

$$u_d \equiv \nabla_d \theta, \quad u_{cd} \equiv \nabla_c \nabla_d \theta \quad (4)$$

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The C-Tensor we defined, earlier in Eq. (3), by :

$$C^{ab} \equiv u_{cd} {}^*R^{d(ab)c} + u_d \epsilon^{dce(a} \nabla_e R^{b)c} \quad (5)$$

is traceless and one can prove that :

$$\nabla_a C^{ab} = -\frac{1}{8} u^b {}^*R R \quad (6)$$

this fact, in vacuum, leads directly to the evolution of θ shown in Eq. (2).

The Energy-Stress Tensor

In the above we used T_{ab} as the Energy-Stress tensor, this is actually :

$$T_{ab} = -\frac{2}{\sqrt{-g}} \left(\frac{\delta \mathcal{L}_{\text{mat}}}{\delta g^{ab}} + \frac{\delta \mathcal{L}_{\theta}}{\delta g^{ab}} \right) \quad (7)$$

This means that T_{ab} consists of two parts. One is :

$$T_{ab}^{\text{mat}} = -\frac{2}{\sqrt{-g}} \frac{\delta \mathcal{L}_{\text{mat}}}{\delta g^{ab}} \quad (8)$$

and the other is, explicitly, given by S_{θ} :

$$T_{ab}^{\theta} = \beta \left[(\nabla_a \theta) (\nabla_b \theta) - \frac{1}{2} g_{ab} (\nabla_a \theta) (\nabla^a \theta) - g_{ab} V(\theta) \right] \quad (9)$$

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One can set :

$$\beta = 0 \quad (10)$$

This immediately yields :

$$T_{ab}^{\theta} \equiv 0 \quad (11)$$

and Eq. (2) is reduced to the constraint :

$${}^*R R = 0 \quad (12)$$

We call the last one the *Pontryagin Constraint*. This constraint is, obviously, independent of θ .

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One can connect the constraint with the Weyl tensor, through :

$${}^*R R = {}^*C C \quad (13)$$

$${}^*C C = \frac{1}{2} \epsilon^{cdef} C^a{}_{bef} C^b{}_{acd} \quad (14)$$

and then by :

$$\left(C_{abcd} + \frac{i}{2} \epsilon_{abef} C^{ef}{}_{cd} \right) v^b v^d = E_{ac} + i B_{ac} \quad (15)$$

to :

$$E_{ab} B^{ab} = 0 \quad (16)$$

This means that we must have either :

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to :

$$E_{ab} B^{ab} = 0 \quad (16)$$

This means that we must have either :

- Purely electrical spacetimes ($B_{ab} = 0$)

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to :

$$E_{ab} B^{ab} = 0 \quad (16)$$

This means that we must have either :

- Purely electrical spacetimes ($B_{ab} = 0$)
- Purely magnetic spacetimes ($E_{ab} = 0$)

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$${}^*C C = \frac{1}{2} \epsilon^{cdef} C^a{}_{bef} C^b{}_{acd} \quad (14)$$

and then by :

$$\left(C_{abcd} + \frac{i}{2} \epsilon_{abef} C^{ef}{}_{cd} \right) v^b v^d = E_{ac} + iB_{ac} \quad (15)$$

to :

$$E_{ab} B^{ab} = 0 \quad (16)$$

This means that we must have either :

- Purely electrical spacetimes ($B_{ab} = 0$)
- Purely magnetic spacetimes ($E_{ab} = 0$)
- Spacetimes where E and B are vertical

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One can also see that the constraint can be written as :

$$\mathfrak{S}(\mathcal{J}) = \mathfrak{S}(\Psi_0\Psi_4 + 3\Psi_2^2 - 3\Psi_1\Psi_3) = 0 \quad (13)$$

for the Weyl spinor \mathcal{J} and the NP scalars $(\Psi_0, \Psi_1, \Psi_2, \Psi_3, \Psi_4)$.

This means that :

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This means that :

- Spacetimes of Petrov Type *III*, *N* and *O* satisfy the constraint

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This means that :

- Spacetimes of Petrov Type *III*, *N* and *O* satisfy the constraint
- Spacetimes of Petrov Type *D*, *II*, and *I* could violate it

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$$\mathfrak{S}(\mathcal{J}) = \mathfrak{S}(\Psi_0\Psi_4 + 3\Psi_2^2 - 3\Psi_1\Psi_3) = 0 \quad (13)$$

for the Weyl spinor \mathcal{J} and the NP scalars $(\Psi_0, \Psi_1, \Psi_2, \Psi_3, \Psi_4)$.

This means that :

- Spacetimes of Petrov Type *III*, *N* and *O* satisfy the constraint
- Spacetimes of Petrov Type *D*, *II*, and *I* could violate it
- The Kerr spacetime and perturbations of it also violate the constraint, since $\Psi_1 = \Psi_3 = 0$ and $\Re(\Psi_2) \neq 0 \neq \mathfrak{S}(\Psi_2)$

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If we consider β to be arbitrary, but non-zero, then θ must satisfy :

$$\beta \square \theta = \beta \frac{dV}{d\theta} - \frac{\alpha}{4} *R R \quad (14)$$

therefore, θ is a dynamic field, which contributes to the energy of the problem by :

$$T_{ab}^{\theta} = \beta \left[(\nabla_a \theta) (\nabla_b \theta) - \frac{1}{2} g_{ab} (\nabla_a \theta) (\nabla^a \theta) - g_{ab} V(\theta) \right] \quad (15)$$

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The equations of motion of the Chern-Simons Modified Gravity are :

■ Modified Einstein Equations

$$G_{ab} + \frac{\alpha}{\kappa} C_{ab} = \frac{1}{2\kappa} T_{ab} \quad (16)$$

with $C^{ab} \equiv u_{cd} {}^*R^{d(ab)c} + u_d \epsilon^{dce(a} \nabla_e R^{b)c}$

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with $C^{ab} \equiv u_{cd} {}^*R^{d(ab)c} + u_d \epsilon^{dce(a} \nabla_e R^{b)c}$

■ Evolution Equation for the Coupling Field θ

$$\beta \square \theta = \beta \frac{dV}{d\theta} - \frac{\alpha}{4} {}^*R R \quad (17)$$

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with $C^{ab} \equiv u_{cd} {}^*R^{d(ab)c} + u_d \epsilon^{dce(a} \nabla_e R^{b)c}$

■ Evolution Equation for the Coupling Field θ

$$\beta \square \theta = \beta \frac{dV}{d\theta} - \frac{\alpha}{4} {}^*R R \quad (17)$$

■ The Energy-Stress Tensor for θ

$$T_{ab}^\theta = \beta \left[(\nabla_a \theta) (\nabla_b \theta) - \frac{1}{2} g_{ab} (\nabla_a \theta) (\nabla^a \theta) - g_{ab} V(\theta) \right] \quad (18)$$

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On the *non-dynamical* framework we set $\beta = 0$ and the evolution of θ reduces to the differential constraint :

$${}^*R R = 0 \quad (16)$$

Therefore in this context :

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$${}^*R R = 0 \quad (16)$$

Therefore in this context :

- θ is arbitrary and usually, chosen as to simplify the equations

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$${}^*R R = 0 \quad (16)$$

Therefore in this context :

- θ is arbitrary and usually, chosen as to simplify the equations
- The constraint above radically reduces the space of solutions of the new theory, since it imposes "heavy" geometrical restrictions

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On the dynamical framework we suppose $\beta \neq 0$, therefore :

- θ is no longer arbitrary and its evolution is governed by

$$\beta \square \theta = \beta \frac{dV}{d\theta} - \frac{\alpha}{4} *R R \quad (16)$$

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- θ is no longer arbitrary and its evolution is governed by

$$\beta \square \theta = \beta \frac{dV}{d\theta} - \frac{\alpha}{4} *R R \quad (16)$$

- Since θ has its own equation of motion, it also introduces extra energy to the problem

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- θ is no longer arbitrary and its evolution is governed by

$$\beta \square \theta = \beta \frac{dV}{d\theta} - \frac{\alpha}{4} *R R \quad (16)$$

- Since θ has its own equation of motion, it also introduces extra energy to the problem
- One should always solve that equation and then try to solve the modified Einstein equations

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- θ is no longer arbitrary and its evolution is governed by

$$\beta \square \theta = \beta \frac{dV}{d\theta} - \frac{\alpha}{4} *R R \quad (16)$$

- Since θ has its own equation of motion, it also introduces extra energy to the problem
- One should always solve that equation and then try to solve the modified Einstein equations
- Arbitrariness is not completely lifted as we introduce an arbitrary potential $V(\theta)$ - although this could be gauged away

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Consider the Schwarzschild line element :

$$ds^2 = - \left(1 - \frac{2M}{r}\right) dt^2 + \left(1 - \frac{2M}{r}\right)^{-1} dr^2 + r^2 (d\vartheta^2 + \sin^2 \vartheta d\phi^2) \quad (17)$$

and also consider $\theta = \theta(t, r, \vartheta, \phi)$. Since ${}^*R R \equiv 0$ for this spacetime, the vanishing of the C Tensor leads to :

$$\partial_\phi \partial_t \theta = \partial_\vartheta \partial_t \theta = \partial_r \left(\frac{\partial_\phi \theta}{r} \right) = \partial_r \left(\frac{\partial_\vartheta \theta}{r} \right) = 0 \quad (18)$$

So, for a choice of $\theta = F(t, r) + rG(\phi, \vartheta)$, Eq. (17) will always be a solution.

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Now we consider the following line element :

$$ds^2 = g_{\alpha\beta}(x^\gamma) dx^\alpha dx^\beta + \Phi(x^\gamma)^2 d\Omega^2 \quad (19)$$

Where $d\Omega$ is the volume element of S^2 with coordinates x^i and $g_{\alpha\beta}$ is a 2D metric tensor with coordinates x^γ .

For this line element :

- $R_{\alpha\beta}$ and R_{ij} are non-vanishing

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- $C_{\alpha i}$ are non-vanishing

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- $C_{\alpha i}$ are non-vanishing
- The modified equations decouple

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For this line element :

- $R_{\alpha\beta}$ and R_{ij} are non-vanishing
- $C_{\alpha i}$ are non-vanishing
- The modified equations decouple

The vanishing of the C -Tensor now leads to :

$$\theta = F(x^\gamma) + \Phi(x^\gamma) G(x^i) \quad (20)$$

And by virtue of Birkhoff's theorem : *The only spherically symmetric solution of the Modified Equations, in the non-dynamical framework, is the Schwarzschild solution*

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Next we consider the Kerr metric :

$$\begin{aligned}
 ds^2 = & - \left(1 - \frac{2Mr}{\Sigma} \right) dt^2 - \frac{4Mar \sin^2 \vartheta}{\Sigma} dt d\phi + \frac{\Sigma}{\Delta} dr^2 + \Sigma d\vartheta^2 + \\
 & + \sin^2 \vartheta \left(r^2 + a^2 + \frac{2Mra^2 \sin^2 \vartheta}{\Sigma} \right) d\phi^2
 \end{aligned} \tag{21}$$

where, $\Sigma = r^2 + a^2 \cos^2 \vartheta$ and $\Delta = r^2 - 2Mr + a^2$. As we already noticed, the Potryagin Constraint is not satisfied. Namely :

$${}^*R R = - \frac{96M^2 r \cos \vartheta}{\Sigma^6} (r^2 - 3a^2 \cos^2 \vartheta) (3r^2 - a^2 \cos^2 \vartheta) \tag{22}$$

Therefore the Kerr Metric is *not* a solution!

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The γ -metric has the following line element, in prolate spheroidal coordinates :

$$\begin{aligned}
 ds^2 = & - \left(\frac{x-m}{x+m} \right)^\gamma dt^2 + \left(\frac{x^2-m^2}{x^2-m^2y^2} \right)^{\gamma^2} \left(\frac{x+m}{x-m} \right)^\gamma \times \\
 & \times (x^2-m^2y^2) \left(\frac{dx^2}{x^2-m^2} + \frac{dy^2}{1-y^2} \right) + \\
 & + \left(\frac{x+m}{x-m} \right)^\gamma (x^2-m^2) (1-y^2) d\phi^2
 \end{aligned} \tag{23}$$

This metric :

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This metric :

- is static and axisymmetric

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This metric :

- is static and axisymmetric
- Represents a Minkowski spacetime if $m = 0$ or $\gamma = 0$

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This metric :

- is static and axisymmetric
- Represents a Minkowski spacetime if $m = 0$ or $\gamma = 0$
- Represents a Schwarzschild spacetime if $\gamma = 1$

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This metric :

- is static and axisymmetric
- Represents a Minkowski spacetime if $m = 0$ or $\gamma = 0$
- Represents a Schwarzschild spacetime if $\gamma = 1$
- Represents a Curzon spacetime if $\gamma \rightarrow \infty$

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This metric :

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- Represents a Minkowski spacetime if $m = 0$ or $\gamma = 0$
- Represents a Schwarzschild spacetime if $\gamma = 1$
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- is of Petrov type D - for $\gamma \neq 1$ and $\gamma \neq 0$

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 \end{aligned} \tag{23}$$

This metric :

- is static and axisymmetric
- Represents a Minkowski spacetime if $m = 0$ or $\gamma = 0$
- Represents a Schwarzschild spacetime if $\gamma = 1$
- Represents a Curzon spacetime if $\gamma \rightarrow \infty$
- is of Petrov type D - for $\gamma \neq 1$ and $\gamma \neq 0$
- is the static limit of the Tomimatsu-Sato family of solutions

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Next we will consider the following choice for the coupling field θ :

$$\theta = \theta(x) \quad (23)$$

The only non-vanishing component of the C -Tensor is :

$$C^{\phi t} = \left[(x^2 - m^2) (1 - \gamma^2) \theta'' + (2x - m\gamma) (1 - \gamma^2) \theta' \right] \frac{B(x, y)}{A(x, y)} \quad (24)$$

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this yields the following differential equation for θ :

$$(x^2 - m^2) (1 - \gamma^2) \theta'' + (2x - m\gamma) (1 - \gamma^2) \theta' = 0 \quad (25)$$

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$$(x^2 - m^2) (1 - \gamma^2) \theta'' + (2x - m\gamma) (1 - \gamma^2) \theta' = 0 \quad (25)$$

This equation has the following solution :

$$\theta = \left(\frac{x - m}{x + m} \right)^{\gamma/2} \quad (26)$$

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To sum up :

- The only Spherically Symmetric Solution is the Schwarzschild Metric
- The Kerr Metric is *not* a solution of the Modified Field Equations
- The γ Metric is a solution of the Modified Field Equations for a specific choice of the coupling field θ

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- The only Spherically Symmetric Solution is the Schwarzschild Metric
- The Kerr Metric is *not* a solution of the Modified Field Equations
- The γ Metric is a solution of the Modified Field Equations for a specific choice of the coupling field θ
- No other, axisymmetric (static or stationary), physically significant solutions have been found, yet.

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- The only Spherically Symmetric Solution is the Schwarzschild Metric
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- The γ Metric is a solution of the Modified Field Equations for a specific choice of the coupling field θ
- No other, axisymmetric (static or stationary), physically significant solutions have been found, yet.

Conclusion : The overconstraining of the modified field equations, due to the *Pontryagin Constraint*, renders the existence of other solutions highly unlikely.

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The Weyl line element in prolate spheroidal coordinates is :

$$ds^2 = -f dt^2 + e^{2k} f^{-1} (x^2 - y^2) \left(\frac{dx^2}{x^2 - 1} + \frac{dy^2}{1 - y^2} \right) + \frac{(x^2 - 1)(1 - y^2)}{f} d\phi^2 \quad (27)$$

Where f and k are functions of x and y only.

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Where f and k are functions of x and y only.

Eq. (27) satisfies ${}^*R R \equiv 0$ so, after setting $V(\theta) \equiv 0$, Eq. (2) yields :

$$\square\theta = 0 \quad (28)$$

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In addition to Eq. (28) the field equations must also satisfy :

$$C_{ab} - 8\pi T_{ab}^{\theta} = 0 \quad (27)$$

This is only true if :

$$\theta = \theta_1(x, y, t) + \theta_2(x, y, \phi) \quad (28)$$

so that the field equations will decouple.

In this case, Eq. (27) along with Eq. (28) lead to a very complex system of PDEs, that is impossible to solve!

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We can describe such spacetimes with the Papapetrou line element (in cylindrical coordinates) :

$$ds^2 = -e^{2U} (dt - \omega d\phi)^2 + e^{-2U} \left[e^{2k} (d\rho^2 + dz^2) + \rho^2 d\phi^2 \right] \quad (29)$$

where ω , U and k are all functions of ρ and z .

For such spacetimes we have, in general :

$${}^*R R \neq 0 \quad (30)$$

This leads to the following equation for θ :

$$\beta \square \theta = -\frac{\alpha}{4} {}^*R R \quad (31)$$

This equation is a non-homogenous version of Eq. (28) and therefore constrains our system of PDEs even more since we also have to solve Eq. (27)

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In the dynamical framework of the Chern-Simons theory :

- θ is a dynamical and not arbitrary field, although one can consider an arbitrary potential $V(\theta)$.

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Summary

In the dynamical framework of the Chern-Simons theory :

- θ is a dynamical and not arbitrary field, although one can consider an arbitrary potential $V(\theta)$.
- When considering static axisymmetric spacetimes we end up with an overconstrained system of PDEs.

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- θ is a dynamical and not arbitrary field, although one can consider an arbitrary potential $V(\theta)$.
- When considering static axisymmetric spacetimes we end up with an overconstrained system of PDEs.
- When considering stationary axisymmetric spacetimes that system gets even more constrained.

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- θ is a dynamical and not arbitrary field, although one can consider an arbitrary potential $V(\theta)$.
- When considering static axisymmetric spacetimes we end up with an overconstrained system of PDEs.
- When considering stationary axisymmetric spacetimes that system gets even more constrained.
- This means that no solution exist except for the trivial ones.

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- When considering static axisymmetric spacetimes we end up with an overconstrained system of PDEs.
- When considering stationary axisymmetric spacetimes that system gets even more constrained.
- This means that no solution exist except for the trivial ones.

We conclude that *no static or stationary axisymmetric solution of General Relativity can also be a solution of Chern-Simons Gravity.*